



# Control-Systems

## Basic Information's

Select from the beginning the best fitting technology



# Controller comparison

Technology	Advantages	Disadvantages
Direct control	<ul style="list-style-type: none"><li>• Cheap</li><li>• Simple cabling</li></ul>	<ul style="list-style-type: none"><li>• Not reliable.</li><li>• High failure rate.</li><li>• Dedicated hardware. One function</li><li>• Gets complicated if even simple logical controls are required.</li><li>• Needs bulky cables to the handset</li></ul>
Relay control	<ul style="list-style-type: none"><li>• Simple but robust control. (Reliable)</li><li>• Thin wires possible btw. Handset and control</li><li>• Simple logic combinations in Handset possible.</li></ul>	<ul style="list-style-type: none"><li>• Needs an additional control box for the relay's</li><li>• Still needs the same amount of wires between Handset and Control box like in case of direct control</li></ul>



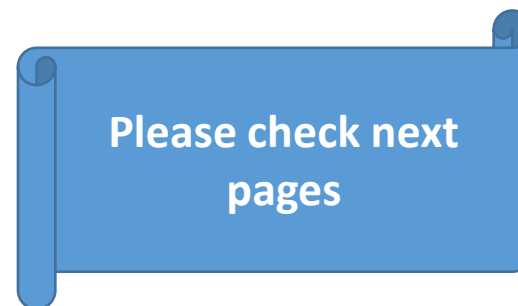
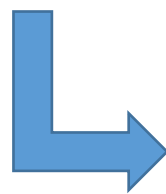
# Controller comparison

Technology	Advantages	Disadvantages
ISP; Programmable Logic	<ul style="list-style-type: none"><li>• Very robust control</li><li>• No Memory loss possible</li><li>• No Power on Delay time</li><li>• Complex logic algorithm possible</li><li>• Timer and counter function</li><li>• Reprogrammable</li><li>• Low stand by current. 0<math>\mu</math>A solutions possible.</li><li>• Per motor only one control wire necessary.</li></ul>	<ul style="list-style-type: none"><li>• More components</li><li>• No Hall sensor feedback possible</li><li>• If analog signals needs to be measured, it get's expensive</li></ul>
$\mu$ -Processor	<ul style="list-style-type: none"><li>• Most flexible</li><li>• High memory capability</li><li>• Complicated control algorithm possible</li><li>• More intelligent motor controls possible. Like torque or current limit.</li><li>• Serial communication (Bus Structure) possible / recommended</li></ul>	<ul style="list-style-type: none"><li>• Higher cost, more components</li><li>• Start up time during Power on</li><li>• Some more failure sources like memory loss or bug related mistakes. Debugging and testing time needs to be heeded.</li><li>• EMC issue pop's up because of Mosfet control and <math>\mu</math>C own Oscillator</li></ul>



# Some Example's

On the next page we would like to show you some example's of control units and some typical application according to the different technologies



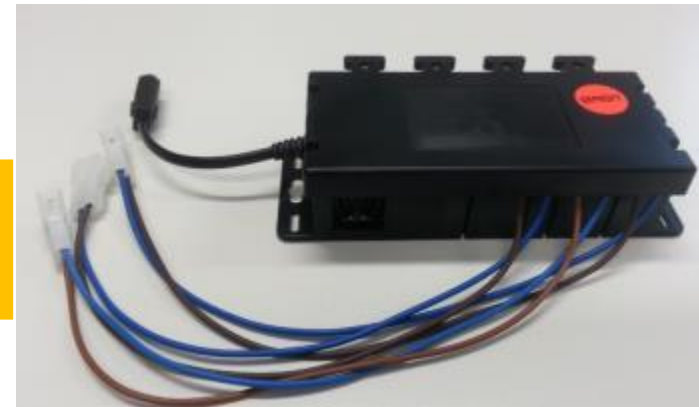


# Simple Relay control

## Pictures:



Universal cable fixing



- Multiple Purpose housing
- With or without cable OUT/INPUT possible
- Protection degree IPx2
- Up to 3 motors independant selectable
- Accu Charging possible through relay PCBA
- Accu and SMPS operation possible
- Different cable connectors possible



# ISP-control box; Programmable Logic

## Pictures:



- Multiple Purpose housing
- Protection degree IPx2
- With or without cable out/input possible
- Up to 4 motors independant selectable
- Different cable connectors possible
- Accu and SMPS operation possible,
- Heating and Massage Control possible
- Free programmable through ISP-Logic



# $\mu$ -Processor controller

## Pictures:



- Multiple Purpose housing
- Accu and SMPS operation possible,
- Heating, Massage, light, Multimedia operation possible
- Up to 6 motors independant selectable
- Free programmable, Diagnose toll, up/download, accessories, test etc. through Windows based Software
- Up to IPx6 depend on the housing
- UL and TÜV approved
- Etc.





# Thank you for your attention

## Additional



## needed

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